7.3 Translation and Partial Fractions

Recall in the examples of Section 7.2, the solution of a linear differential equation can be reduced to finding the inverse Laplace transform of a function

$$R(s) = rac{P(s)}{Q(s)}$$

where the degree of P(s) is less than Q(s).

Question 1: How to decompose R(s)?

The following two rules describe the partial fraction decomposition of R(s), in terms of the factorization of the denominator Q(s) into linear factors (rule 1) and irreducible quadratic factors (rule 2).

Rule 1. Linear Factor Partial Fractions

The portion of the partial fraction decomposition of R(s) corresponding to the linear factor s - a of multiplicity n is a sum of n partial fractions, having the form

$$rac{A_1}{s-a}+rac{A_2}{(s-a)^2}+\cdots+rac{A_n}{(s-a)^n},$$

where A_1, A_2, \cdots , and A_n are constants.

Rule 2. Quadratic Factor Partial fractions

The portion of the partial fraction decomposition corresponding to the irreducible quadratic factor $(s-a)^2 + b^2$ of multiplicity n is a sum of n partial fractions, having the form

$$rac{A_1s+B_1}{(s-a)^2+b^2}+rac{A_2s+B_2}{[(s-a)^2+b^2]^2}+\cdots+rac{A_ns+B_n}{[(s-a)^2+b^2]^n},$$

where A_1, A_2, \dots, A_n , B_1, B_2, \dots , and B_n are constants.

Question 2: How to find F(s-a) if $F(s) = \mathcal{L}{f(t)}$?

Theorem 1. Translation on the s-Axis

If $F(s) = \mathcal{L}\{f(t)\}$ exists for s > c, then $\mathcal{L}\{e^{at}f(t)\}$ exists for s > a+c, and

$$\mathcal{L}\{e^{at}f(t)\} = F(s-a).$$

Equivalently,

$$\mathcal{L}^{-1}\{F(s-a)\} = e^{at}f(t).$$

Thus the translation $s \to s - a$ in the transform corresponds to multiplication of the orginal function of t by e^{at} .

Proof:

$$F(s-a)=\int_0^\infty e^{-(s-a)t}f(t)dt=\int_0^\infty e^{-st}[e^{at}f(t)]dt=\mathcal{L}\{e^{at}f(t)\}.$$

We apply the translation theorem to the formulas for the Laplace transforms of t^n , $\cos kt$ and $\sin kt$, we have

| f(t) | F(s) | |
|--------------------------------|---------------------------|---------|
| e ^{at} t ⁿ | $\frac{n!}{(s-a)^{n+1}}$ | (s > a) |
| $e^{at}\cos kt$ | $\frac{s-a}{(s-a)^2+k^2}$ | (s > a) |
| $e^{at} \sin kt$ | $\frac{k}{(s-a)^2 + k^2}$ | (s > a) |

We can also check Table 1 to get the solution
Example 1 Apply the translation theorem to find the Laplace transforms of the functions.
(1)
$$x(t) = t^3 e^{3t}$$
 $a = -3$, $f(t) = \cos 5\pi t$ $a = 3$. $f(t) = t^3$
(2) $x(t) = e^{-3t} \cos 5\pi t$ $a = -3$, $f(t) = \cos 5\pi t$ $a = 3$. $f(t) = t^3$
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(1) Recall $d = 2t^3 f = \frac{3!}{t^4}$. By Thm 1. $d = t^3 f = f(t) = F(t) = F(t) = F(t)$
We have $d = 2t^3 f = \frac{3!}{t^4} = \frac{3!}{(t-3)^4}$
(2) Recall $d = 2t^3 f = \frac{3!}{(t-3)^4}$
(3) Recall $d = 2t^3 f = \frac{5}{5^2 f (5\pi)^4}$.
By Thm 1. $d = 2t^3 f = \frac{5}{(5+3)^2 f + 25\pi^2}$
 $= \frac{5+3}{(5+3)^2 f + 25\pi^2}$

Example 2 Apply the translation theorem to find the inverse Laplace transform of the function.

$$F(s) = rac{3s+5}{s^2-6s+25}$$

ANS:
$$F(s) = \frac{3s+s}{s^2-6s+2s} = \frac{3s+s}{s^2-6s+9-9+2s} = \frac{3(s-3)+9+5}{(s-3)^2+16}$$

 $= 3 \cdot \frac{s-3}{(s-3)^2+4^2} + \frac{14}{2} \cdot \frac{2}{(s-3)^2+4^2}$
 $= 3 \cdot \frac{s-3}{(s-3)^2+4^2} + \frac{7}{2} \cdot \frac{2}{(s-3)^2+4^2}$
Then by Table 1.
 $\mathcal{L}^{-1}[F(s)] = 3 \cdot \mathcal{L}^{-1}[\frac{s-3}{(s-3)^2+4^2}] + \frac{7}{2} \cdot \mathcal{L}^{-1}[\frac{9}{(s-3)^2+4^2}]$
 $= 3 \cdot e^{3t} \cos 4t + \frac{7}{2} \cdot e^{3t} \sin 4t$.

Example 4 Use partial fractions to find the inverse Laplace transforms of the functions.

(1)
$$\frac{3s+19}{s^2+6s+34}$$

(2) $\frac{3s+19}{s^2-2s^2-8s}$
ANS: (1) $F_{1}(s) = \frac{3s+19}{s^2+6s+34} = \frac{3s+19}{s^2+6s+9-9+34} = \frac{3s+19}{(s+3)^2+25}$
 $= \frac{3(s+3)^{-9} + 19}{(s+3)^2 + 5^2} = 3 \frac{s+3}{(s+3)^25^2} + 2 \cdot \frac{5}{(s+3)^25^2}$
Apply Table 1. with $a = -3$
 $J_{-1}^{-1} \gamma F_{1}(s) = 3 \cdot J_{-1}^{-1} \gamma \frac{s+3}{(s+3)^25^2} + 2 \cdot \frac{5}{(s+3)^25^2} = 3 \cdot e^{-35} \cdot \cos 551 + 2 \cdot e^{-31} \cdot \sin 512$
(2) $R_{1}(s) = \frac{s^2+1}{s^3-2s^5-8s} = \frac{s^2+1}{s(s^2-2s-8)} = \frac{s^2+1}{s(s-4)(s+2)} = \frac{P_{1}(s)}{Q_{1}(s)}$
So $Q(s) = s(s+2)(s-4)$. By Rule 1, we can write
 $R_{1}(s) = \frac{s^2+1}{s(s+2)(s-4)} = -\frac{A}{s} + \frac{B}{s+2} + \frac{C}{s-4}$
 $= \frac{A(s+2)(s-4) + Bs(s-4) + Cs(s+2)}{s(s+2)(s-4)}$
Compare the numerators, we have
 $s^2+1 = A(s+2)(s-4) + Bs(s-4) + Cs(s+2)$
If we substitute $s=0, s=-2, s=4$, respectively, we have
 $\int_{1}^{1} f_{1} = -\frac{8A}{s} = \int_{1}^{1} \frac{B-5}{s}$

Thus $R(s) = -\frac{1}{2} \cdot \frac{1}{2} + \frac{1}{2} \cdot \frac{1}{2} + \frac{1}{24} \cdot \frac{1}{54}$ $L^{-1} R(s) = -\frac{1}{2} + \frac{1}{24} e^{-2t} + \frac{1}{24} e^{4t}$ Example 5 Use Laplace transforms to solve the initial value problem.

$$x''-4x=3t; x(0)=x'(0)=0.$$